

CLAIMS:

1. A method of composing an image [IM], the method comprising a step of mapping [MAP] a set of image sample values [SV] from a departure space [DEP] to an arrival space [ARR] in accordance with a geometrical transformation [T], the method comprising the steps of

- 5 - computing a zone in the departure space [ITL] by applying the inverse geometrical transformation $[T^{-1}]$ to a zone in the arrival space [TL] covering a group of image samples;
- establishing a group of input values [IV] for the zone in the departure space [ITL], the group of input values [IV] comprising Boolean values [BV], a Boolean input value having a certain position (x_d, y_d) in the departure space and designating the other values having the same position as being non-valid if the position is outside the set of image sample values;
- 10 - composing the group of image samples [TL] from the group of input values [IV], the Boolean values [BV] preventing the input values designated as being non-valid from contributing to an image sample.
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2. A device for composing an image [IM], the composition comprising a step of mapping [MAP] a set of image sample values [SV] from a departure space [DEP] to an arrival space [ARR] in accordance with a geometrical transformation [T], the device being arranged to perform the steps of

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- computing a zone in the departure space [ITL] by applying the inverse geometrical transformation $[T^{-1}]$ to a zone in the arrival space [TL] covering a group of image samples;
- establishing a group of input values [IV] for the zone in the departure space [ITL], the group of input values [IV] comprising Boolean values [BV], a Boolean input value having a certain position (x_d, y_d) in the departure space and designating the other values having the same position as being non-valid if the position is outside the set of image sample values;
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- composing the group of image samples [TL] from the group of input values [IV], the Boolean values [BV] preventing the input values designated as being non-valid from contributing to an image sample.

- 5 3. A computer program product for an image composition device, the computer program product comprising a set of instructions which, when loaded into the image composition device, cause the device to map [MAP] a set of image sample values [SV] from a departure space [DEP] to an arrival space [ARR] in accordance with a geometrical transformation [T] by performing the steps of
- 10 - computing a zone in the departure space [ITL] by applying the inverse geometrical transformation $[T^{-1}]$ to a zone in the arrival space [TL] covering a group of image samples;
- establishing a group of input values [IV] for the zone in the departure space [ITL], the group of input values [IV] comprising Boolean values [BV], a Boolean input value
- 15 having a certain position (x_d, y_d) in the departure space and designating the other values having the same position as being non-valid if the position is outside the set of image sample values;
- composing the group of image samples [TL] from the group of input values [IV], the Boolean values [BV] preventing the input values designated as being non-valid
- 20 from contributing to an image sample.